Fig. 4 shows the variation of backscattered power due to the variation of dielectric thickness h for normal incidence.

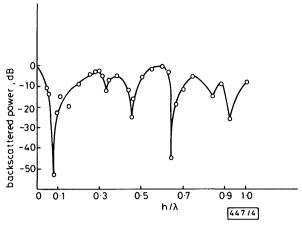


Fig. 4 Variation of backscattered power with dielectric thickness for normal incidence

$$f = 9.850 \,\text{GHz}, a = 0.5d, d = \lambda$$

The low backscatter for normal incidence can be explained as a consequence of eqn. 1 when $\theta_i = 0$, i.e. the diffraction angle will be 90°. The backscattered power is plotted by rotating the receiver along the circumference of a circle with the geometric centre of the plate as the centre in the horizontal plane (Fig. 5). The maximum diffracted power is obtained when the receiving angle becomes 90°. The same result is obtained when $\theta_i = 90^\circ$, i.e. when the incident ray is parallel to the plane of the grating.

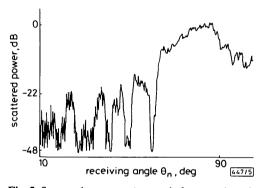


Fig. 5 Scattered power against angle for normal incidence $f = 9.840 \,\text{GHz}, \, a = 0.5d, \, h = 0.08 \,\lambda$

Conclusion: The problem of eliminating normal and nearnormal incidence specular reflection is solved using a selfcomplementary strip grating. This could not be achieved using conventional rectangular metallic corrugations. Fabricating corrugations on the metal surface is a tedious process, which can be avoided by using strips on the dielectric sheet with a reflector. To reduce the multipath interference from buildings and to solve the problem of air traffic control systems at airports and instrument landing system interference etc., we can use strip gratings of the appropriate period and thickness. The fabrication of metallic corrugated horns giving symmetrical beams with a low sidelobe level is a difficult task. However, by employing a strip grating structure for the walls of a horn, we may obtain better performance with the additional advantage of easier construction technique and lower cost.

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EVALUATION OF CROSSTALK PENALTY IN MULTICHANNEL ASK HETERODYNE OPTICAL COMMUNICATION SYSTEMS

Indexing terms: Optical communications, Crosstalk

The bit error rate (BER) of a two-channel ASK heterodyne lightwave system employing envelope detection is evaluated analytically. The result is used to calculate the power penalty resulting from intrachannel crosstalk. To main a BER below 10^{-9} , the power penalty increases from 0.2 to 1 dB when the level of crosstalk increases from -15 to -10 dB. The theory predicts a minimum channel spacing of three times the bit rate if the design criterion is to keep the crosstalk penalty below 0.1 dB. The minimum channel spacing increases to five times the bit rate for multichannel systems when crosstalk from the nearest neighbours on both sides is included.

Introduction: One of the attractions of coherent communication systems is the possibility of simultaneous transmission of a large number of closely spaced channels using frequencydivision multiplexing techniques. An important issue for such multichannel coherent systems concerns the minimum interchannel spacing that must be maintained before the intercrosstalk significantly degrades the performance. Although this issue has recently been addressed both theoretically and experimentally, 1-4 a detailed analysis of the effect of crosstalk on the system performance does not appear to have been carried out. In this letter we calculate the crosstalk-induced power penalty for two-channel ASK heterodyne systems employing envelope detection, and discuss the minimum channel spacing needed to keep the power penalty below a prespecified level. The extension to multichannel systems is straightforward, and the analysis can also be extended to the case of FSK systems. For multichannel ASK heterodyne systems, the theory predicts a minimum channel spacing of five times the bit rate if the design criterion is to keep the crosstalk penalty below 0.1 dB. This is in agreement with the recent theoretical² and experimental⁴ estimates.

Theory: The output of a balanced heterodyne receiver can be written as³

$$I = 2R\sqrt{(P_{LO}P_1)m_1 \cos(2\pi f_{IF}t)} + 2R\sqrt{(P_{LO}P_2)m_2 \cos[2\pi (f_{IF} + D)t + \phi] + N(t)}$$
(1)

where R is the detector responsivity, f_{IF} is the intermediate frequency, D is the channel spacing, P_{LO} is the local-oscillator power, P_1 is the signal-channel power and P_2 is the power of the interfering channel. The relative phase ϕ generally varies from bit to bit in a random manner. The ASK modulation is represented by m_1 and m_2 , which take values of 1 and 0 depending on the bit pattern. N(t) accounts for various noise sources (shot noise, circuit noise etc.) and is taken to be a Gaussian process with a white spectral density. The effect of laser phase noise (both at the transmitter and the local oscillator) can be included by taking

$$f_{IF} = f_0 + \Delta f \tag{2}$$

where f_0 is the average value and Δf accounts for random fluctuations due to phase noise. In general Δf changes randomly during a bit period.

The received signal is passed through a bandpass filter centred on f_0 and an envelope detector. Although the filter bandwidth W is chosen judiciously to transmit most of the signal-channel energy while effectively blocking the neighbouring channels, the filter nevertheless intercepts a small fraction of the energy from the neighbouring channels. This constitutes the crosstalk signal that interferes with the post-detection processing of channel 1. The crosstalk depends on whether a '1' or a '0' is received by channel 2, and both possibilities should be considered. Since the two symbols are equally likely to occur, the bit error rate (BER) or the error probability P_e is given by

$$P_{e} = \frac{1}{2}(P_{e1} + P_{e0}) \tag{3}$$

where P_{e1} and P_{e0} are the error probabilities for the cases of receiving a '1' or a '0' in the interfering channel, respectively.

To evaluate P_{e1} , we note that the output of the envelope detector is given by

$$x = [(m_1 A + B \cos \phi + N_c)^2 + (B \sin \phi + N_s)^2]^{1/2}$$
 (4)

where N_c and N_s are the quadrature components of the noise, A is the data signal and B is the interfering signal due to crosstalk. A and B depend on the received power as well as on the bit rate and the filter bandwidth W. Their explicit expressions are

$$A = 2R \left[(P_{LO} P_1)^{1/2} \int_{-W/2}^{W/2} \operatorname{sinc} \left[\pi T_1 (f - \Delta f) \right] T_1 df \right]$$
 (5)

and

$$B = 2R \left[(P_{LO} P_2)^{1/2} \int_{-W/2}^{W/2} \operatorname{sinc} \left[\pi T_2 (f + D - \Delta f) \right] T_2 df \right]$$
 (6)

where $B_j = 1/T_j$ is the bit rate of channel j, sinc $(x) = \sin(x)/x$ and we have assumed a rectangular input pulse and an ideal filter $[H(f) = 0 \text{ for } | f - f_0| > W/2]$. Both A and B are in general random variables because of frequency fluctuations Δf . In this letter we neglect the effect of laser phase noise by assuming that T_j $\Delta f \ll 1$. The error probability P_{e1} is given by $\frac{1}{2}$

$$P_{e1} = \frac{1}{2} \int_{0}^{\nu_{T}} p_{1}(x) dx + \frac{1}{2} \int_{\nu_{T}}^{\infty} p_{0}(x) dx$$
 (7)

where $p_1(x)$ and $p_0(x)$ are the probability densities for the '1' and '0' symbols in channel 1, respectively. More specifically, both are Rician distributions;⁵ i.e.

$$p_0(x) = \frac{x}{\sigma^2} I_0\left(\frac{Bx}{\sigma^2}\right) \exp\left(-\frac{x^2 + B^2}{2\sigma^2}\right)$$
 (8)

and $p_1(x)$ is obtained by replacing B by $(A^2 + B^2 + 2AB \times \cos \phi)^{1/2}$. Here $I_0(y)$ is the modified Bessel function of order zero and σ^2 is the noise variance (proportional to the filter bandwidth W).

The decision threshold V_T in eqn. 7 is chosen to minimise P_e . In the absence of crosstalk, $V_T \simeq A/2$ for $A/\sigma \gg 1$, and we assume it to be the same even in the presence of crosstalk. This is generally also the case in practice. It can be shown that the contribution of the first term in eqn. 7 is smaller by about a factor of A/σ compared to the second term, and can be neglected. This simplifies the calculation considerably since P_e becomes independent of ϕ . In the general case P_e should be averaged over ϕ . The second integral can be performed analytically with the result

$$P_{e1} \simeq \frac{1}{2} \exp\left(-\frac{A^2}{8\sigma^2}\right) f(A, B, \sigma) \tag{9}$$

where

$$f(A, B \sigma) = \exp\left(-\frac{B^2}{2\sigma^2}\right) \sum_{m=0}^{\infty} \left(\frac{2B}{A}\right)^m I_m \left(\frac{AB}{2\sigma^2}\right)$$
(10)

represents the enhancement of the error probability in the presence of crosstalk. P_{e0} is obtained by setting B=0 in eqn. 9, and is given by

$$P_{e0} \simeq \frac{1}{2} \exp\left(-\frac{A^2}{8\sigma^2}\right) \tag{11}$$

This is the well known expression for the BER in the absence of crosstalk.⁵ Using eqns. 9 and 11 in eqn. 3, the BER of a two-channel ASK system is given by

$$P_e = \frac{1}{4} \exp\left(-\frac{A^2}{8\sigma^2}\right) [f(A, B, \sigma) + 1]$$
 (12)

Results: Eqn. 12 was used to study the variation of P_e with A/σ for different values of the parameter B/σ . These BER curves show that a higher value of A/σ is needed to maintain a certain BER in the presence of crosstalk, resulting in a power penalty. The penalty becomes significant when the crosstalk is comparable to the noise level. The power penalty can be calculated by noting that the BER for a single channel is given by

$$\bar{P}_e = \frac{1}{2} \exp\left(-\bar{A}^2 / 8\sigma^2\right)$$
 (13)

where \bar{A} is the value of A in the absence of crosstalk $(\bar{A}/\sigma = 12.65 \text{ for a BER of } 10^{-9})$. By setting $P_e = \bar{P}_e$, A/\bar{A} can be obtained. The power penalty (in decibels) is then given by

$$\Delta = 20 \log \left(A/\bar{A} \right) \tag{14}$$

Fig. 1 shows the variation of Δ with the crosstalk at a given BER. The level of crosstalk (in decibels) is defined by

$$C = 10 \log (B/A) \tag{15}$$

The curve shown in Fig. 1 is universal (at a given BER) in the sense that the power penalty depends on a single crosstalk parameter C. Of course, the value of C depends on the received power ratio P_2/P_1 as well as on the filter bandwidth W, channel spacing D and the channel bit rates B_1 and B_2 . Fig. 2 shows the variation of crosstalk C with D/B_2 after assuming $P_1 = P_2$, $B_1 = B_2$ and $W = 2B_1$. The oscillatory structure is due to the sinc function in eqns. 5 and 6. The crosstalk decreases with an increase in channel spacing and falls below $-20 \, \mathrm{dB}$ for $D/B_2 > 4$.

Discussion: From the standpoint of system design, the relevant question is how close two channels can operate without introducing a significant power penalty. If we assume that the maximum tolerable penalty $\Delta = 0.1 \, \mathrm{dB}$, from Fig. 1 the cross-

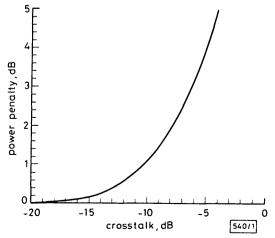


Fig. 1 Power penalty as a function of crosstalk BER = 10^{-9}

talk should be $<-17\,\mathrm{dB}$. Fig. 2 shows that $C<-17\,\mathrm{dB}$ if $D/B_2 \ge 3$, i.e. the minimum channel spacing is about three times the bit rate. In the case of multichannel operation the dominant contribution to crosstalk comes from the nearest neighbours located on each side of the signal channel. When the analysis is extended to include both interfering channels, the results show that a minimum channel spacing of five times the bit rate² can ensure a negligible crosstalk penalty. These results assume equal received powers and equal bit rates for the two channels. For $P_2 > P_1$, the crosstalk increases by a

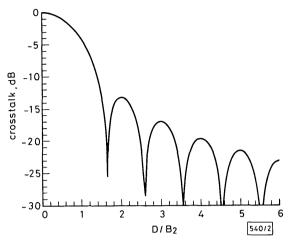


Fig. 2 Crosstalk as a function of normalised channel spacing $W = 2B_1$, $B_2 = B_1$

BIREFRINGENT-FIBRE POLARISATION SPLITTERS

Indexing terms: Optical fibres, Optical couplers

A simple analytical study on fused tapered couplers composed of birefringent fibres is presented. It is shown that the polarisation splitting property of the coupler can remain almost constant over a wide range of wavelengths when the geometrical birefringence and the stress-induced birefringence in the coupler are properly balanced.

Introduction: Polarisation splitting has been observed in fused tapered single-mode fibre couplers made of nonbirefringent fibres^{1,2} or birefringent fibres.^{3,4} The operation of such devices relies on the difference in the coupling coefficient between the two orthogonal polarisation modes.¹⁻⁴ In a non-birefringent-fibre coupler, this difference is caused purely by the geometrical birefringence (or form birefringence) arising from the noncircular cross-section of the coupler, and is found to increase approximately with the square of the wavelength.⁵⁻⁷ In a birefringent-fibre coupler, the stress-induced birefringence can also cause polarisation splitting,⁴ and, as we shall show, this effect diminishes with increasing wavelength. It is thus expected that a balance of these two birefringences in a coupler can make the polarisation splitting characteristic of the coupler insensitive to wavelength variation.

Analysis and results: We consider a fused tapered birefringent-fibre coupler with core radius ρ_1 and cladding radius ρ_2 . The refractive indices of the cladding and the surrounding material are n_2 and n_3 , respectively. For the sake of simplicity, we assume that material birefringence is stress-induced only in the core region. The refractive index of the cores is thus denoted by n_{1x} for the x-polarised mode and n_{1y} for the y-polarised mode, where we assume that $n_{1y} > n_{1x}$. The polarisation splitting property of the coupler is described by the difference between the coupling coefficients of the x- and y-polarised modes, $C_x - C_y$, which can be written as

$$C_x - C_y = \delta C_G + \delta C_S \tag{1}$$

where δC_G and δC_S represent the geometrical and stress-induced effects, respectively. We assume that the effects of the

factor of $\sqrt{(P_2/P_1)}$, and a larger channel spacing would be required. Similarly, the minimum channel spacing may increase because of phase noise when the IF linewidth Δf_{IF} becomes comparable to the bit rate. The results presented here assume that $\Delta f_{IF} \ll B_1$ and B_2 . The conclusions are expected to remain valid for $\Delta f_{IF} < 0.1B_1$, a condition often satisfied in practice.

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cores on δC_G are negligible, and thus have⁵⁻⁷

$$\delta C_G = q_G \frac{(2\Delta_2)^{3/2}}{\rho_2 V^2} \tag{2}$$

where $V=2\pi\rho_2\,n_2(2\Delta_2)^{1/2}/\lambda$ is the normalised frequency with λ the free-space wavelength, $\Delta_2=(n_2^2-n_3^2)/2n_2^2$ is the cladding-substrate index profile height, and q_G is a constant depending on the cross-section of the coupler. The stress-induced component δC_S can be easily derived from the results in Reference 6:

$$\delta C_{S} = q_{S} \frac{\rho_{1}^{2} BV}{\rho_{2}^{3} n_{2} (2\Delta_{2})^{1/2}}$$
(3)

where $B=n_{1y}-n_{1x}$ is the material birefringence and q_S is a structure-dependent constant. That δC_S increases linearly with B at a given wavelength is consistent with the results in Reference 4. If we assume that q_G and q_S are both positive, it is clear that δC_G is inversely proportional to $V^2(\lambda^{-2})$, while δC_S is proportional to $V(\lambda^{-1})$. However, we should point out that eqns. 2 and 3, which are accurate at small V-values, 6 provide only qualitative knowledge at large V-values. From eqns. 2 and 3 the V-value at which $\delta C_G = \delta C_S$, denoted by V_X , is given by

$$V_{X} = \left[\frac{q_{G}}{q_{S}} \left(\frac{\rho_{2}}{\rho_{1}} \right)^{2} \frac{n_{2} (2\Delta_{2})^{2}}{B} \right]^{1/3} \tag{4}$$

It follows that the minimum $C_x - C_y$, where $d(C_x - C_y)/dV = 0$, occurs at $V = V_M$, where

$$V_{M} = 2^{1/3} V_{X} \tag{5}$$

If the coupler is operated at V_M , its polarisation splitting property will be least sensitive to wavelength variation.

To quantify our discussion, we analyse a rectangular coupler with square cores. This structure is a good model for a practical stadium-shaped coupler.^{4,7} The constants q_G and q_S are given by^{5,6}

$$q_G = \frac{3\pi^2 \rho_2^3}{(2\rho_2 + d)^3} \tag{6}$$